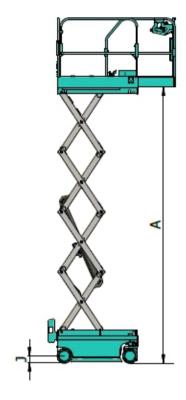
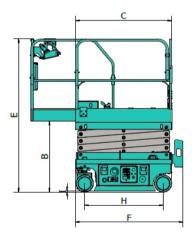
SWSLD607DCElectric Driven Scissor Scissor-type Aerial Work Platform

SUNW\(\hat{N}\)RD

Dimension					
Working height*		6.5m			
Α	Platform height maximum	4.5m			
В	Platform height (stowed)	0.95m			
С	Platform length	1.29m			
	Slide-out platform extension deck	0.6m			
D	Platform width	0.7m			
Е	Stowed height (rails up)	2.06m			
	Stowed height (rails down)	1.7m			
F	Overall length	1.44m			
G	Overall width	0.76m			
Н	Wheelbase	1.05m			
I	Ground clearance (stowed)	0.06m			
J	Ground clearance (raised)	0.017m			



Performance	
Lift capacity	240kg
Lift capacity (extension deck)	100kg
Max. platform pccupancy	2
Drive speed (stowed)	4.0km/h
Drive speed (elevated)	0.8km/h
Turning radius (inside)	0.4m
Turning radius (outside)	1.6m
Raise / lower speed	23s / 25s
Gradeability**	30%
Max. allowable working angle (lateral / longitudinal)	1.5° / 3°
Controls	Proportional
Wheel driver	DC motor real drive
Multiple disc brakes	Dual front wheel
Tires	230mm×80mm
Battery	4×6V/85Ah
Charger	24V/15A
Weight	890kg





- * Working height is equal to Platform height plus 2m.
- * Climbing ability is suitable for driving on slopes; Refer to Operator Manual for slope level.

SWSL0607DC

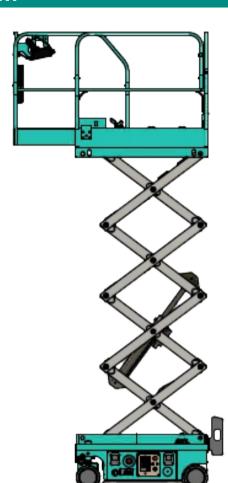
Electric Driven Scissor Scissor-type Aerial Work Platform

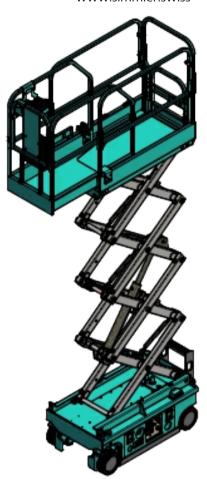


Buechstr. 25, 8645 Jona 055 212 69 50 www.simmler.swiss









Standard features

◆ Proportional control	Extended platform	◆ Folding guardrails platform	◆ Self-lock gate on platform
◆ Solid tire	Hour meter	Standard transport forklift hole	◆ Safety maintenance support rod
◆ Horn	◆ Flashing beacon	Action beep	◆ DC motor drive
◆ Pit protection device	◆ Emergency descent system	◆ Emergency stop button	Automatic brakes system
◆ Tilt sensor with alarm	Charging protection system	◆ Fault diagnosis system	

Options features

◆ Air line to platform	◆ AC power to platform	GPS tracking system	◆ Platform work lights
◆ Maintenance-free battery	Lithium battery and management system	Intelligent interconnection system	Overload protection system

